



From Space to Time: Enabling Adaptive Safety with Learned Value Functions via Disturbance Recasting



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Paper

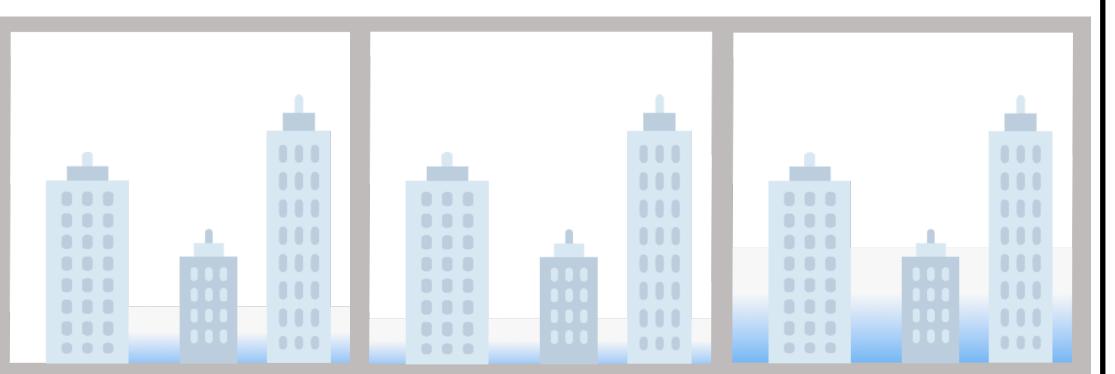
t = 0

Motivation and Background:

Website



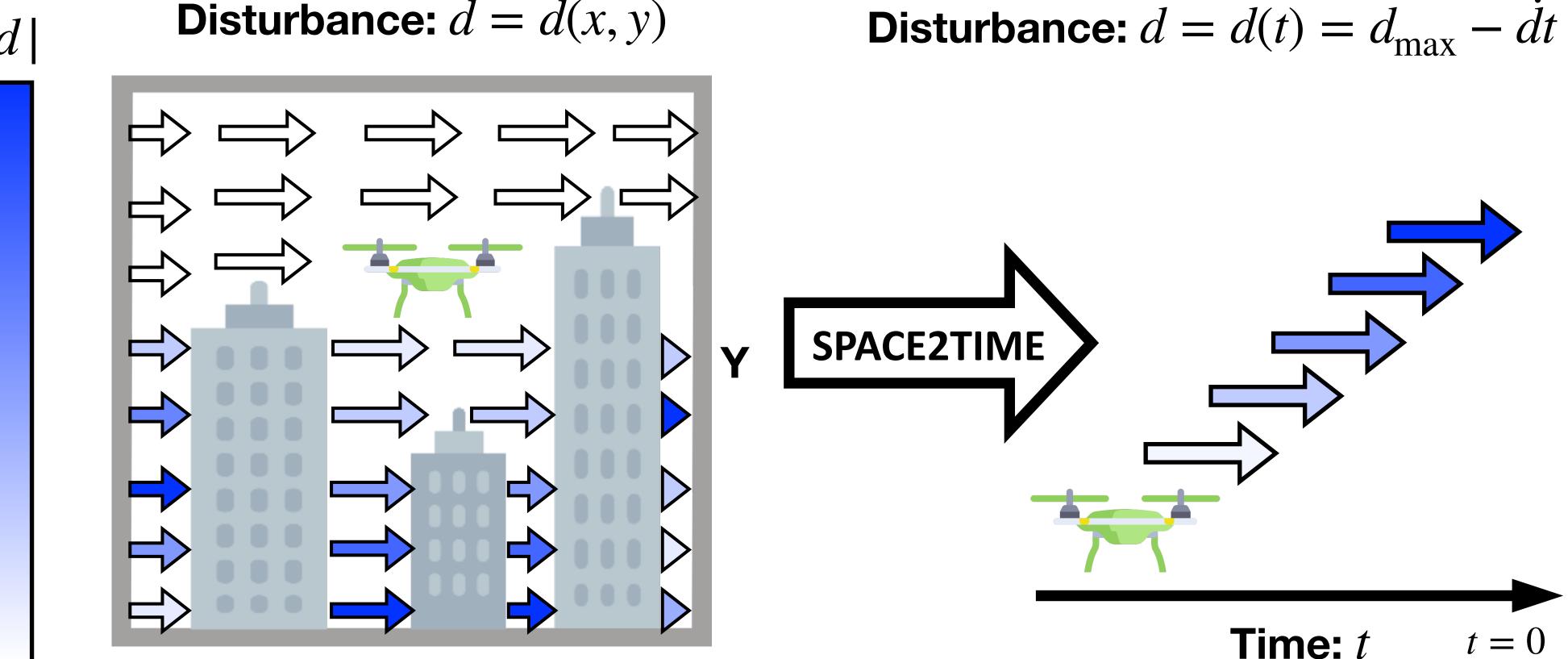
Not accounting for spatial variation in wind can lead to catastrophic failures during drone flight



Learned value functions are not amenable to online fine tuning, and learning a separate value function for every possible spatial variation is infeasible

Key Idea: Reparamaterize spatial variations in disturbance as temporal variations.

Disturbance: d = d(x, y)



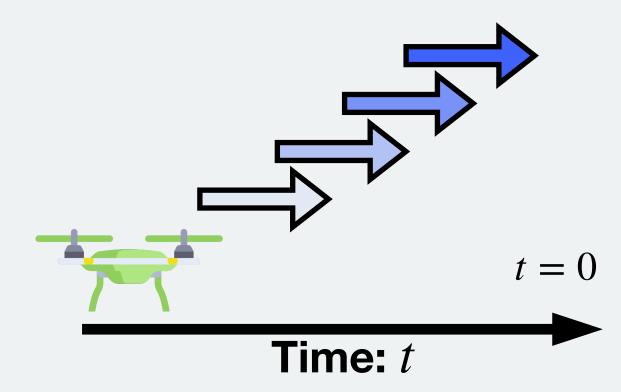
Enables learning safety value functions offline and using them in spatial varying environments online. SPACE2TIME ensures the system is *realistic* about the present (based on current disturbance) and pessimistic about the future (assuming worst measured rate of disturbance change to persist)

Safe Target Region

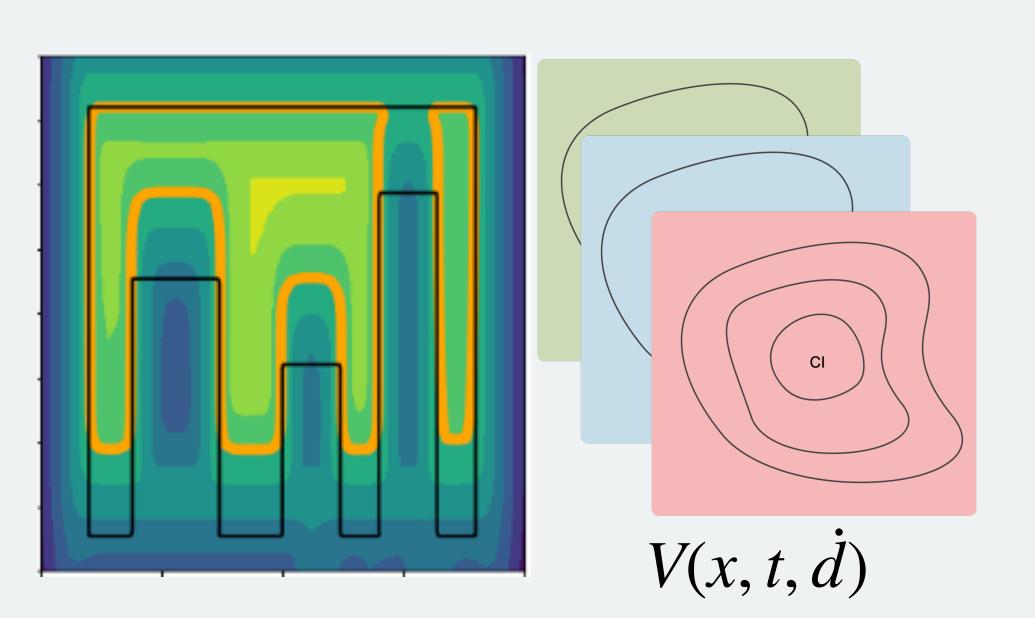
1. Define Safe Backup Set

SPACE2TIME: Offline

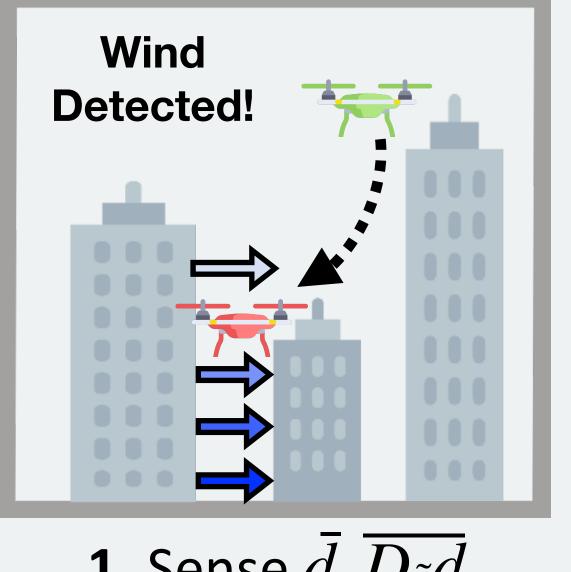
Disturbance: $d = d(t) = d_{\text{max}} - dt$



2. Temporal Disturbance Encoding



3. Learn/Compute Value Functions

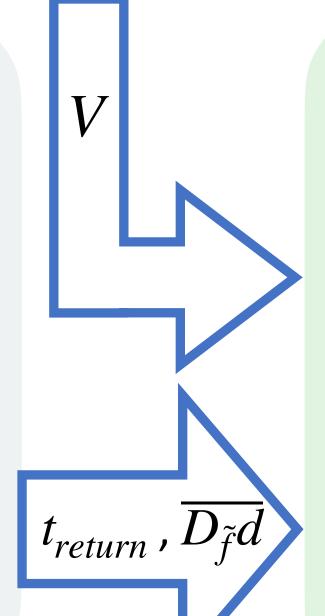


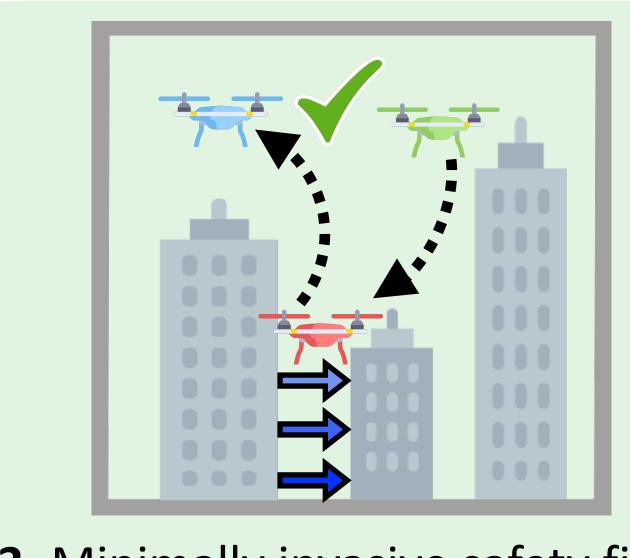
1. Sense $d, \overline{D_{\tilde{f}}d}$

SPACE2TIME: Online Hz



2. Compute t_{return} : time to return to safe set

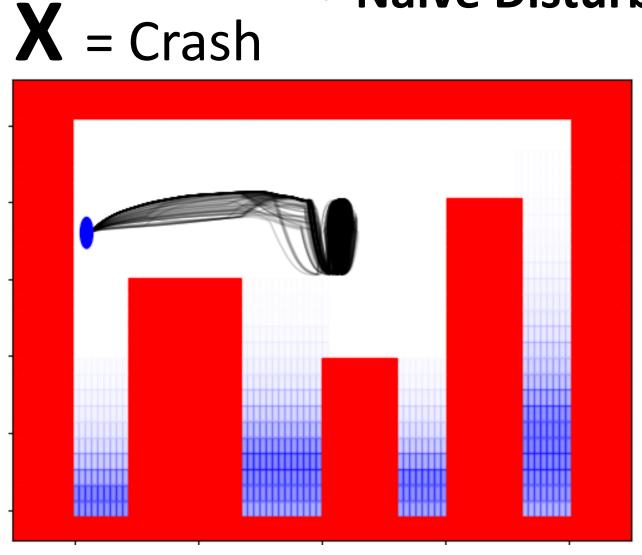




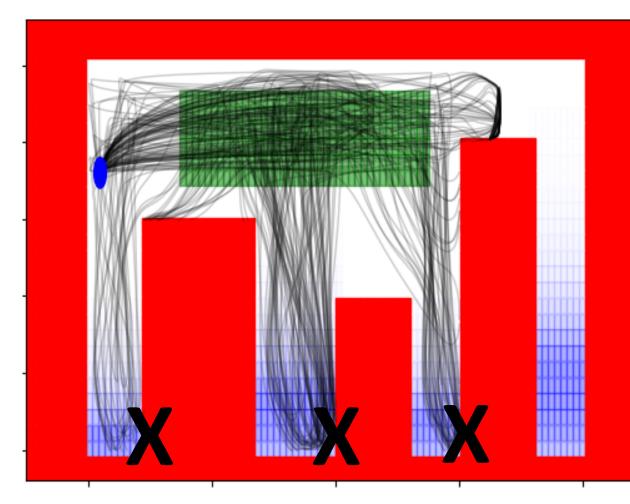
3. Minimally invasive safety filter using: $V(x, t_{return}, D_{\tilde{f}}d)$

Results:

- Naive Worst Case: Safety filter assuming worst case disturbance magnitude bounds
- Naive Disturbance Switching: Switching safety filter to use disturbance bounds compatible with most recent observations

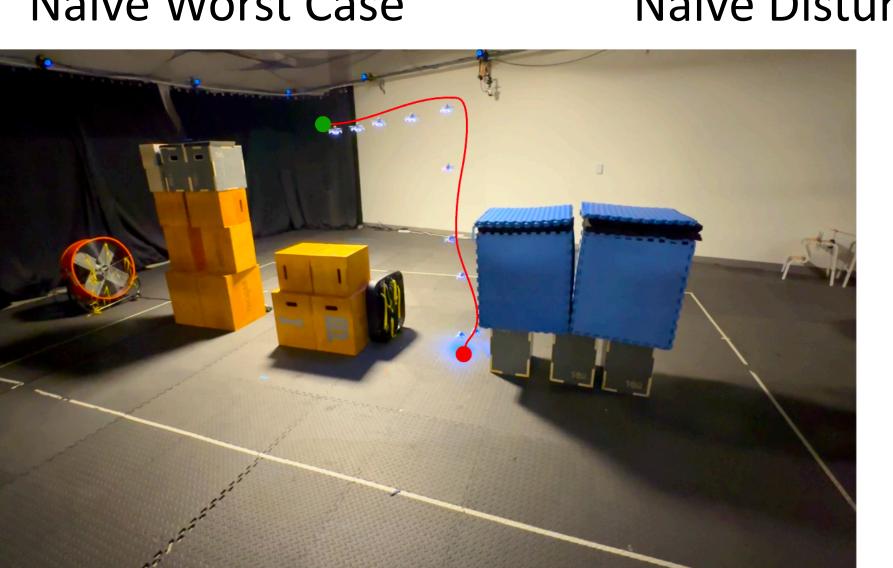




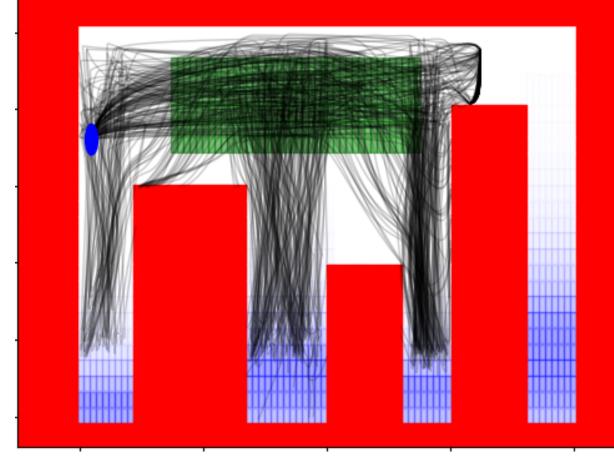


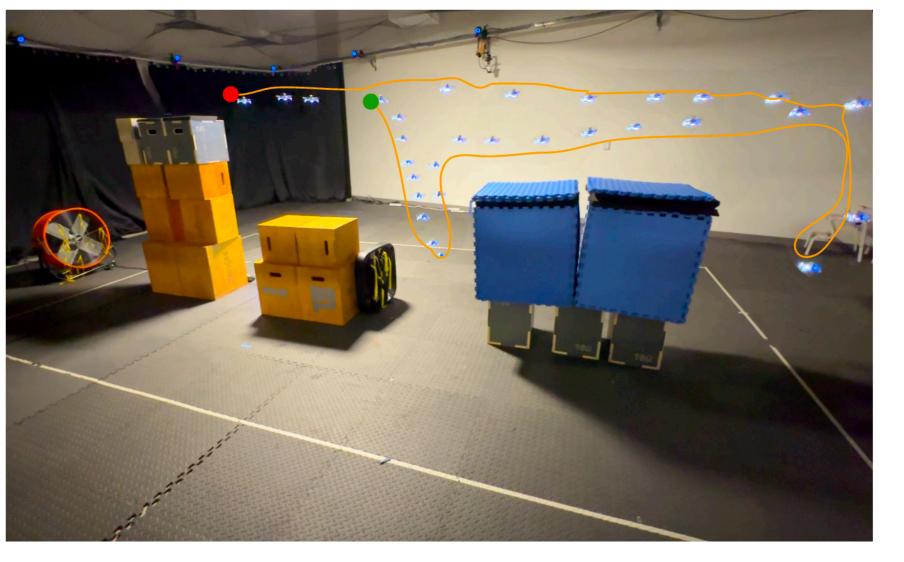
Naive Disturbance Switching

SPACE2TIME

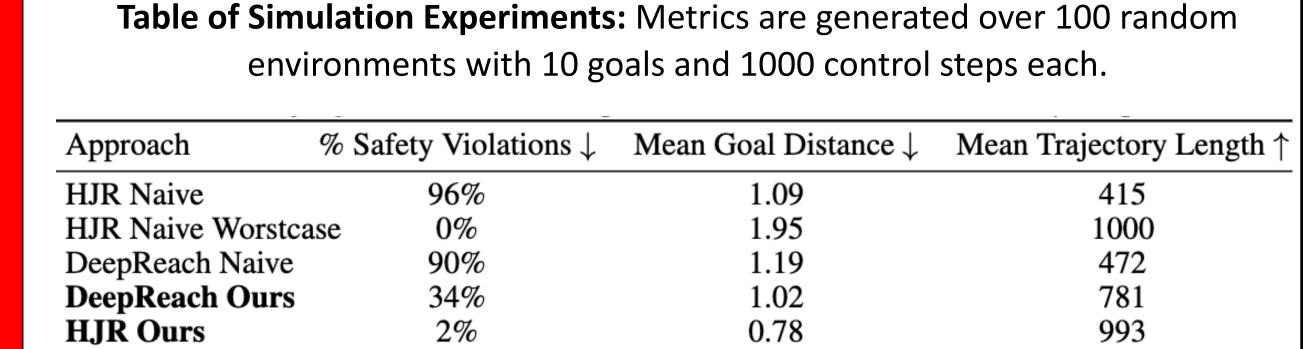


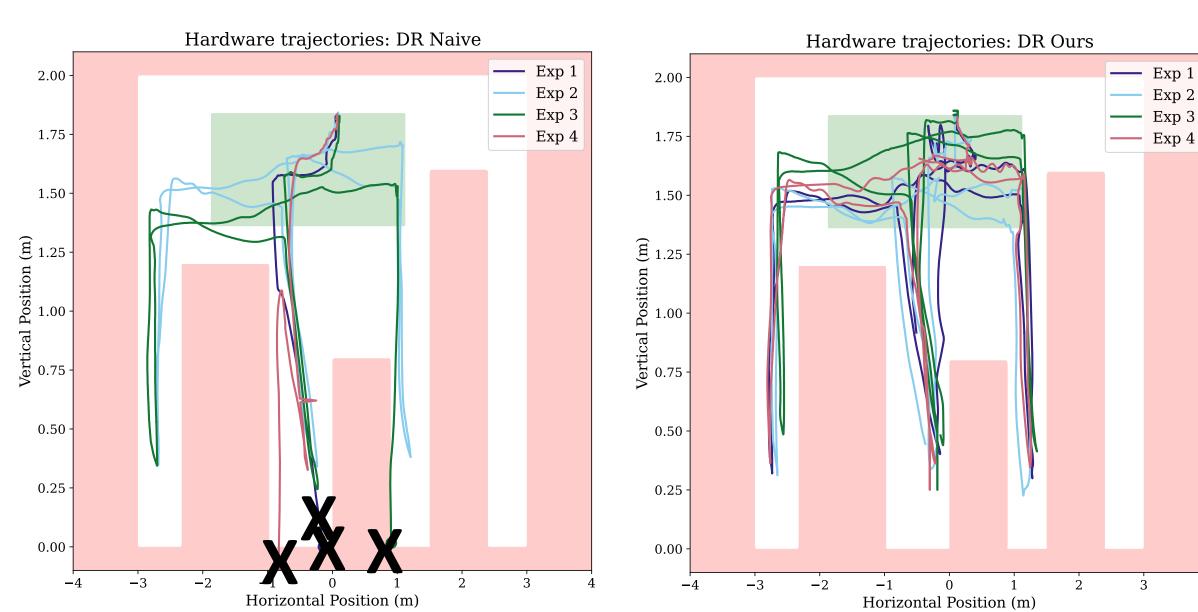
Naive Disturbance Switching





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Naive Disturbance Switching

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